# Appendix to "A Lasso-Type Approach for Estimation and Variable Selection in Single Index Models" published in the Journal of Computational and Graphical Statistics 

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Proof of Proposition 1. Let $Y_{j}=\left(y_{1}-\tilde{y}_{j}, y_{2}-\tilde{y}_{j}, \ldots, y_{n}-\tilde{y}_{j}\right)^{T}, X_{j}=\left(x_{1}-\tilde{x}_{j}, x_{2}-\right.$ $\left.\tilde{x}_{j}, \ldots, x_{n}-\tilde{x}_{j}\right)^{T}, W_{j}=\operatorname{diag}\left(w_{1 j}, w_{2 j}, \ldots, w_{n j}\right)$. Then the target function

$$
L_{\lambda}(b, \theta)=\sum_{j=1}^{n} \sum_{i=1}^{n}\left(y_{i}-\tilde{y}_{j}-b_{j} \theta^{T}\left(x_{i}-\tilde{x}_{j}\right)\right)^{2} w_{i j}+\lambda \sum_{j=1}^{n}\left|b_{j}\right| \sum_{k=1}^{p}\left|\theta_{k}\right|
$$

can be re-written as

$$
L(b, \theta)=\sum_{j=1}^{n}\left[\left(Y_{j}-X_{j} b_{j} \theta\right)^{T} W_{j}\left(Y_{j}-X_{j} b_{j} \theta\right)+\lambda \sum_{k=1}^{p}\left|b_{j} \theta_{k}\right|\right]
$$

We have

$$
\begin{aligned}
L(b, \theta) & =\sum_{j=1}^{n}\left[Y_{j}^{T} W_{j} Y_{j}-2 b_{j} \theta^{T} X_{j}^{T} W_{j} Y_{j}+b_{j} \theta^{T} X_{j}^{T} W_{j} X_{j} b_{j} \theta+\lambda \sum_{k=1}^{p}\left|b_{j} \theta_{k}\right|\right] \\
& \geq \sum_{j=1}^{n}\left[Y_{j}^{T} W_{j} Y_{j}-2 b_{j} \theta^{T} X_{j}^{T} W_{j} Y_{j}+\lambda \sum_{k=1}^{p}\left|b_{j} \theta_{k}\right|\right]
\end{aligned}
$$

The above inequality follows from the fact that $b_{j} \theta^{T} X_{j}^{T} W_{j} X_{j} b_{j} \theta \geq 0$. Recall that $R_{j}=$ $X_{j}^{T} W_{j} Y_{j}$. Therefore,

$$
L(b, \theta) \geq \sum_{j=1}^{n}\left[Y_{j}^{T} W_{j} Y_{j}+\sum_{k=1}^{p}\left(\lambda-2 r_{j k} \operatorname{sgn}\left(b_{j} \theta_{k}\right)\right)\left|b_{j} \theta_{k}\right|\right]
$$

where $\operatorname{sgn}(\cdot)$ is the sign function. Further recall that $r_{11}=\max \left|r_{j k}\right|$. When $\lambda \geq 2\left|r_{11}\right|$, $\lambda-2 r_{j k} \operatorname{sgn}\left(b_{j} \theta_{k}\right) \geq 0$ for all $j$ and $k$, and thus $L(b, \theta) \geq \sum_{j=1}^{n} Y_{j}^{T} W_{j} Y_{j}$. The minimum is achieved at $b_{j}=0$ and arbitrary $\theta$. Therefore, $b_{j}(\lambda)=0$ and $\theta$ is not identifiable when $\lambda \geq 2\left|r_{11}\right|$.

Assume that the second largest $\left|r_{j k}\right|$ is $\left|r_{j_{2} k_{2}}\right|$. Consider $\lambda \in\left(2\left|r_{j_{2} k_{2}}\right|, 2\left|r_{11}\right|\right)$. Following argument similar to the above, we conclude that $b_{j}(\lambda)=0$ for $j \geq 2$. Therefore, we only need to minimize

$$
L_{1}\left(b_{1}, \theta\right)=\left(Y_{1}-X_{1} b_{1} \theta\right)^{T} W_{1}\left(Y_{1}-X_{1} b_{1} \theta\right)+\lambda \sum_{k=1}^{p}\left|b_{1} \theta_{k}\right|,
$$

which is the Lasso with weight least squares. Applying existing results of the regular Lasso or using the KKT conditions, it is easy to show that there exists $\delta>0$ such that for $\lambda \in$ $\left(2\left|r_{11}\right|-\delta, 2\left|r_{11}\right|\right)$, the minimizer of $L_{1}\left(b_{1}, \theta\right)$ is $b_{1} \theta_{1}=\left[\sum_{i=1}^{n}\left(x_{i 1}-\tilde{x}_{i 1}\right)^{2} w_{i 1}\right]^{-1}\left[r_{11}-\operatorname{sgn}\left(r_{11}\right) \lambda / 2\right]$ and $b_{1} \theta_{k}=0$ for $2 \leq k \leq p$. Therefore,

$$
\hat{b}_{1}(\lambda)=\left[\sum_{i=1}^{n}\left(x_{i 1}-\tilde{x}_{i 1}\right)^{2} w_{i 1}\right]^{-1}\left[r_{11}-\operatorname{sgn}\left(r_{11}\right) \lambda / 2\right], \quad \text { and } \quad \theta(\lambda)=(1,0,0, \ldots, 0)^{T} .
$$

Proof of Proposition 2. Let $b_{j}^{+}$and $b_{j}^{-}$denote the positive and negative parts of $b_{j}(1 \leq$ $j \leq n)$ and let $\theta_{k}^{+}$and $\theta_{k}^{-}$denote the positive and negative parts of $\theta_{k}(1 \leq k \leq p)$. Let $\theta^{+}=$ $\left(\theta_{1}^{+}, \theta_{2}^{+}, \ldots, \theta_{p}^{+}\right)^{T}, \theta^{-}=\left(\theta_{1}^{-}, \theta_{2}^{-}, \ldots, \theta_{p}^{-}\right)^{T}, b^{+}=\left(b_{1}^{+}, b_{2}^{+}, \ldots, b_{n}^{+}\right)^{T}$, and $b^{-}=\left(b_{1}^{-}, b_{2}^{-}, \ldots, b_{n}^{-}\right)^{T}$. Then, $\theta=\theta^{+}-\theta^{-}$and $b=b^{+}-b^{-}$. The sim-lasso problem can be re-written as to minimize

$$
\begin{equation*}
L(b, \theta)=Q(b, \theta)+\lambda \sum_{j=1}^{n}\left(b_{j}^{+}+b_{j}^{-}\right) \sum_{k=1}^{p}\left(\theta_{k}^{+}+\theta_{k}^{-}\right) \tag{1}
\end{equation*}
$$

subject to $\theta_{k}^{+} \geq 0, \theta_{k}^{-} \geq 0, b_{j}^{+} \geq 0, b_{j}^{-} \geq 0, \theta_{k}^{+} \theta_{k}^{-}=0$ and $b_{j}^{+} b_{j}^{-}=0$ for $1 \leq k \leq p$ and $1 \leq j \leq n$. It is not difficult to verify that the last two constraints will be satisfied by the minimizer of (1) automatically and thus are redundant. Therefore, they are dropped in the discussion below. The KKT conditions given below characterize the minimizer of (1).

$$
\begin{aligned}
& \frac{\partial L}{\partial b_{j}^{+}}-u_{j}^{+}=\frac{\partial Q}{\partial b_{j}}+\lambda \sum_{k=1}^{p}\left|\theta_{k}\right|-u_{j}^{+}=0 \\
& \frac{\partial L}{\partial b_{j}^{-}}-u_{j}^{-}=-\frac{\partial Q}{\partial b_{j}}+\lambda \sum_{k=1}^{p}\left|\theta_{k}\right|-u_{j}^{-}=0 \\
& \frac{\partial L}{\partial \theta^{+}}-v^{+}=\frac{\partial Q}{\partial \theta}+\lambda \sum_{j=1}^{n}\left|b_{j}\right|-v^{+}=0 \\
& \frac{\partial L}{\partial \theta^{-}}-v^{-}=-\frac{\partial Q}{\partial \theta}+\lambda \sum_{j=1}^{n}\left|b_{j}\right|-v^{-}=0
\end{aligned}
$$

where $u_{j}^{+}, u_{j}^{-}, v^{+}=\left(v_{1}^{+}, \ldots, v_{k}^{+}\right)$, and $v^{-}=\left(v_{1}^{-}, \ldots, v_{k}^{-}\right)$are Lagrange (dual) variables such that $u_{j}^{+} \geq 0, u_{j}^{-} \geq 0, v_{k}^{+} \geq 0, v_{k}^{-} \geq 0, u_{j}^{+} b_{j}^{+}=u_{j}^{-} b_{j}^{-}=0, v_{k}^{+} \theta_{k}^{+}=v_{k}^{-} \theta_{k}^{-}=0$. For any $j \in \mathcal{B}$, $b_{j} \neq 0$, which implies either $b_{j}^{+} \neq 0$ or $b_{j}^{-} \neq 0$. If $b_{j}^{+} \neq 0$, then $u_{j}^{+}=0$; if $b_{j}^{-} \neq 0$, then $u_{j}^{-}=0$. In either case, the following equation holds

$$
\frac{\partial Q}{\partial b_{j}}=-\operatorname{sgn}\left(b_{j}\right) \lambda \sum_{k=1}^{p}\left|\theta_{k}\right| .
$$

When both $u_{j}^{+}>0$ and $u_{j}^{-}>0$, then,

$$
\left|\frac{\partial Q}{\partial b_{j}}\right|<\lambda \sum_{k=1}^{p}\left|\theta_{k}\right|
$$

This implies that $b_{j}=0$ and $j \in \mathcal{B}^{c}$. Whenever $b_{j}$ with $j \in \mathcal{B}$ becomes zero or $u_{j}^{+}$or $u_{j}^{-}$with $j \in \mathcal{B}^{c}$ becomes zero, the corresponding data point need to be removed from $\mathcal{B}$ or added to $\mathcal{B}$ for reconsideration. Combining these facts together gives (iii) and (iv) of the proposition. Similarly we can obtain (i) and (ii) of the proposition.

Proof of Proposition 3. We have

$$
\frac{\partial Q}{\partial \theta}=-2 \sum_{j=1}^{n} \sum_{i=1}^{n}\left(y_{i}-\tilde{y}_{j}-b_{j} \theta^{T}\left(x_{i}-\tilde{x}_{j}\right)\right) w_{i j} b_{j}\left(x_{i}-\tilde{x}_{j}\right)=-2 \sum_{j=1}^{n} b_{j} R_{j}+2 \sum_{j=1}^{n} b_{j}^{2} S_{j} \theta
$$

and

$$
\frac{\partial Q}{\partial b_{j}}=-2 \sum_{i=1}^{n}\left(y_{i}-\tilde{y}_{j}-b_{j} \theta^{T}\left(x_{i}-\tilde{x}_{j}\right)\right) w_{i j} \theta^{T}\left(x_{i}-\tilde{x}_{j}\right)=-2 R_{j}^{T} \theta+2 b_{j} \theta^{T} S_{j} \theta
$$

for $1 \leq j \leq n$. Suppose at a fixed $\lambda$ which is not a transition value, the active sets are $\mathcal{A}$ and $\mathcal{B}$. From Proposition 2, we have

$$
\begin{equation*}
-2 \sum_{j \in \mathcal{B}} b_{j} R_{j \mathcal{A}}+2 \sum_{j \in \mathcal{B}} b_{j}^{2} S_{j \mathcal{A}} \theta_{\mathcal{A}}+\operatorname{sgn}\left(\theta_{\mathcal{A}}\right) \lambda \sum_{j \in \mathcal{B}}\left|b_{j}\right|=0 \tag{2}
\end{equation*}
$$

and for $j \in \mathcal{B}$,

$$
\begin{equation*}
-2 R_{j \mathcal{A}}^{T} \theta_{\mathcal{A}}+2 b_{j} \theta^{T} S_{j} \theta+\operatorname{sgn}\left(b_{j}\right) \lambda \sum_{k \in \mathcal{A}}\left|\theta_{k}\right|=0 \tag{3}
\end{equation*}
$$

When $\lambda$ is between two consecutive transition values, $\theta_{\mathcal{A}}$ and $b_{j}$ 's do not change signs. Differentiating the two sides of (2) and (3) with respect to $\lambda$, we have

$$
\sum_{j \in \mathcal{B}} b_{j}^{2} S_{j \mathcal{A}} \frac{\partial \theta_{\mathcal{A}}}{\partial \lambda}+\sum_{j \in \mathcal{B}} U_{j \mathcal{A}} \frac{\partial b_{j}}{\partial \lambda}+\frac{1}{2} \operatorname{sgn}\left(\theta_{\mathcal{A}}\right) \sum_{j \in \mathcal{B}}\left|b_{j}\right|=0
$$

and for $j \in \mathcal{B}$,

$$
U_{j \mathcal{A}}^{T} \frac{\partial \theta_{\mathcal{A}}}{\partial \lambda}+\theta_{\mathcal{A}}^{T} S_{j \mathcal{A}} \theta_{\mathcal{A}} \frac{\partial b_{j}}{\partial \lambda}+\frac{1}{2} \operatorname{sgn}\left(b_{j}\right) \sum_{k \in \mathcal{A}}\left|\theta_{k}\right|=0
$$

where

$$
U_{j \mathcal{A}}=-R_{j \mathcal{A}}+2 b_{j} S_{j \mathcal{A}} \theta_{\mathcal{A}}+\lambda \operatorname{sgn}\left(b_{j}\right) \operatorname{sgn}\left(\theta_{\mathcal{A}}\right) / 2
$$

Solving the above two equations for the derivatives of $\theta_{\mathcal{A}}$ and $b_{\mathcal{B}}$ leads to the formulas given in the proposition.

