

Math 2660 Topics in Linear Algebra, Key

5.5

1,2,4,11,12,15,19

- 1 (a) $(1,0)(0,1)^T = 0$, (c) $(1,-1)(1,1)^T = 0$, (d) $\frac{1}{2}(\sqrt{3},1)\frac{1}{2}(-1,\sqrt{3})^T = 0$ so they form orthogonal basis of \mathbb{R}^2 . (The answer of the book misses (c)).
- 2 (a) $\mathbf{u}_1^T \mathbf{u}_2 = \mathbf{u}_1^T \mathbf{u}_3 = \mathbf{u}_2^T \mathbf{u}_3 = 0$ and $\|\mathbf{u}_1\|_2 = \|\mathbf{u}_2\|_2 = \|\mathbf{u}_3\|_2 = 1$ so they are orthonormal. Since $\dim \mathbb{R}^3 = 3$, $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthonormal basis of \mathbb{R}^3 .

(b) Let $\mathbf{x} = (1, 1, 1)^T$. Then

$$\mathbf{x} = (\mathbf{x}^T \mathbf{u}_1)\mathbf{u}_1 + (\mathbf{x}^T \mathbf{u}_2)\mathbf{u}_2 + (\mathbf{x}^T \mathbf{u}_3)\mathbf{u}_3 = -\frac{2}{3\sqrt{2}}\mathbf{u}_1 + \frac{5}{3}\mathbf{u}_2 + 0 \cdot \mathbf{u}_3$$

Then $\|x\| =$

- 4 (a) $x_1^T x_2 = 0$ and $\|x_1\|^2 = \|x_2\|^2 = \cos^2 \theta + \sin^2 \theta = 1$. So x_1 and x_2 are orthonormal vectors. Since $\dim \mathbb{R}^2 = 2$, $\{x_1, x_2\}$ is an orthonormal basis of \mathbb{R}^2 .
- (b) Let $y = (y_1, y_2)^T \in \mathbb{R}^2$. Then $y = (y^T x_1)x_1 + (y^T x_2)x_2 = (y_1 \cos \theta + y_2 \sin \theta)x_1 + (-y_1 \sin \theta + y_2 \cos \theta)x_2$.
- (c) $\mathbf{x} - \mathbf{p} = (1, 1, 1, 1)^T - \frac{1}{3}(4, 1, 1, 0)^T = \frac{1}{3}(-1, 2, 2, 3)^T$ and $\mathbf{p}^T(\mathbf{x} - \mathbf{p}) = \frac{1}{3}(4, 1, 1, 0) \cdot \frac{1}{3}(-1, 2, 2, 3)^T = 0$. Hence $\mathbf{p} \perp \mathbf{x} - \mathbf{p}$.
- (d) $\|\mathbf{x} - \mathbf{p}\|_2 = \frac{1}{3}\sqrt{18} = \sqrt{2}$.
 $\|\mathbf{p}\|_2 = \frac{1}{3}\sqrt{18} = \sqrt{2}$.
 $\|\mathbf{x}\|_2 = 2$. Now $\mathbf{x} = \mathbf{p} + (\mathbf{x} - \mathbf{p})$ and $\mathbf{p} \perp \mathbf{x} - \mathbf{p}$. Pythagorean law is satisfied: $2^2 = (\sqrt{2})^2 + (\sqrt{2})^2$.

11 Since Q orthogonal implies $Q^T = Q^{-1}$ (p.259), then $Q = (Q^{-1})^T = (Q^T)^{-1}$. In other words, $QQ^T = I$, i.e., Q^T is orthogonal.

12 Let θ be the angle between $Q\mathbf{x}$ and $Q\mathbf{y}$ and let γ be the angle between \mathbf{x} and \mathbf{y} . Notice that $\|P\mathbf{x}\|_2^2 = (P\mathbf{x})^T P\mathbf{x} = \mathbf{x}^T P^T P\mathbf{x} = \mathbf{x}^T \mathbf{x} = \|\mathbf{x}\|_2^2$ and similarly $\|P\mathbf{y}\|_2^2 = \|\mathbf{y}\|_2^2$. Then

$$\cos \theta = (P\mathbf{x})^T P\mathbf{y} / (\|P\mathbf{x}\|_2 \|P\mathbf{y}\|_2) = \mathbf{x}^T P^T P\mathbf{y} / (\|\mathbf{x}\|_2 \|\mathbf{y}\|_2) = \mathbf{x}^T \mathbf{y} / (\|\mathbf{x}\|_2 \|\mathbf{y}\|_2) = \cos \gamma.$$

So $\theta = \gamma$ as $\theta, \gamma \in [0, \pi]$.

15 Since $Q^T Q = I$, $(\det Q)^2 = \det Q^T \det Q = \det(Q^T Q) = \det I = 1$. So $|\det Q| = 1$, i.e., $\det Q$ is 1 or -1 .

19 By Exercise 17, $UU^T = I$. Outer product form (p.78) of UU^T is $\mathbf{u}_1 \mathbf{u}_1^T + \cdots + \mathbf{u}_n \mathbf{u}_n^T$ where $U = [\mathbf{u}_1 \cdots \mathbf{u}_n]$