

## Math 2660 Topics in Linear Algebra, Key

### 5.2

1a,b,2,3,4

**Warning:**  $R(A)$  denotes the range of  $A$ , i.e., it is the column space of  $A$ . So  $R(A^T)$  is the row space of  $A$ . I made the changes on Key 3.6.

$$1 \quad (a) \quad R(A^T) = \text{Row}(A): \begin{bmatrix} 3 & 4 \\ 6 & 8 \end{bmatrix} \xrightarrow{R_2 - 2R_1} \begin{bmatrix} 3 & 4 \\ 0 & 0 \end{bmatrix}. \text{ So } \{(3, 4)\} \text{ is a basis for } R(A^T).$$

$$R(A) = \text{Col}(A): A^T = \begin{bmatrix} 3 & 6 \\ 4 & 8 \end{bmatrix} \xrightarrow{\frac{1}{3}R_1} \begin{bmatrix} 1 & 2 \\ 4 & 8 \end{bmatrix} \xrightarrow{R_2 - 4R_1} \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}. \text{ So } \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\} \text{ is a basis for } \text{Col}(A).$$

$$N(A): \left[ \begin{array}{cc|c} 3 & 4 & 0 \\ 6 & 8 & 0 \end{array} \right] \xrightarrow{R_2 - 2R_1} \left[ \begin{array}{cc|c} 3 & 4 & 0 \\ 0 & 0 & 0 \end{array} \right]. \text{ So } x_2 = t \text{ and } x_1 = -\frac{4}{3}t. \text{ Then } \mathbf{x} = \frac{1}{3}t(-4, 3) \text{ are the solution to } A\mathbf{x} = \mathbf{0}. \text{ Thus } \{(-4, 3)^T\} \text{ is a basis of } N(A).$$

$$N(A^T): \left[ \begin{array}{cc|c} 3 & 6 & 0 \\ 4 & 8 & 0 \end{array} \right] \xrightarrow{\frac{1}{3}R_1} \left[ \begin{array}{cc|c} 1 & 2 & 0 \\ 4 & 8 & 0 \end{array} \right] \xrightarrow{R_2 - 4R_1} \left[ \begin{array}{cc|c} 1 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]. \text{ So } x_2 = t \text{ and } x_1 = -2t. \text{ Thus } x = t(-2, 1) \text{ are the solutions to } A^T\mathbf{x} = \mathbf{0}. \text{ Thus } \{(-2, 1)^T\} \text{ is a basis of } N(A^T).$$

$$(b) \quad R(A^T) = \text{Row}(A): \begin{bmatrix} 1 & 3 & 1 \\ 2 & 4 & 0 \end{bmatrix} \xrightarrow{R_2 - 2R_1} \begin{bmatrix} 1 & 3 & 1 \\ 0 & -2 & -2 \end{bmatrix}. \text{ So } \{(1, 3, 1), (0, -2, -2)\} \text{ is a basis for } R(A^T).$$

$$R(A) = \text{Col}(A): A^T = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 1 & 0 \end{bmatrix} \xrightarrow{R_2 - 3R_1} \begin{bmatrix} 1 & 2 \\ 0 & -2 \\ 0 & -2 \end{bmatrix} \xrightarrow{R_3 - R_2} \begin{bmatrix} 1 & 2 \\ 0 & -2 \\ 0 & 0 \end{bmatrix} \xrightarrow{-\frac{1}{2}R_2} \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}. \text{ So } \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \text{ is a basis for } \text{Col}(A).$$

$$N(A): \left[ \begin{array}{ccc|c} 1 & 3 & 1 & 0 \\ 2 & 4 & 0 & 0 \end{array} \right] \xrightarrow{R_2 - 2R_1} \left[ \begin{array}{ccc|c} 1 & 3 & 1 & 0 \\ 0 & -2 & -2 & 0 \end{array} \right]. \text{ So } x_3 = t, x_2 = -t \text{ and } x_1 = 2t. \text{ Then } \mathbf{x} = t(2, -1, 1) \text{ are the solution. Thus } \{(2, -1, 1)^T\} \text{ is a basis of } N(A).$$

$$N(A^T): \left[ \begin{array}{cc|c} 1 & 2 & 0 \\ 3 & 4 & 0 \\ 1 & 0 & 0 \end{array} \right] \xrightarrow{R_2 - 3R_1} \left[ \begin{array}{cc|c} 1 & 2 & 0 \\ 0 & -2 & 0 \\ 0 & -2 & 0 \end{array} \right] \xrightarrow{R_3 - R_2} \left[ \begin{array}{cc|c} 1 & 2 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 0 \end{array} \right] \xrightarrow{-\frac{1}{2}R_2} \left[ \begin{array}{cc|c} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]. \text{ So the system has trivial solution only. Thus the empty set } \phi \text{ is the basis of } N(A^T).$$

$$2 \quad (a) \quad S^\perp = \{(x_1, x_2, x_3)^T : (x_1, x_2, x_3) \cdot (1, -1, 1) = 0\} = \{(x_1, x_2, x_3)^T : x_1 - x_2 + x_3 = 0\}. \text{ Set } x_3 = t, x_2 = s \text{ so that } x_1 = s - t. \text{ Thus } \mathbf{x} = s(1, 1, 0)^T + t(-1, 0, 1)^T. \text{ Hence } \{(1, 1, 0)^T, (-1, 0, 1)^T\} \text{ is a basis.}$$

$$(b) \quad S \text{ corresponds to a line } \ell \text{ in } \mathbb{R}^3 \text{ that passes through the origin and the point } (1, -1, 1). \text{ So } S^\perp \text{ represents a plane in } \mathbb{R}^3 \text{ that passes through the origin and is normal to } \ell.$$

3 (a) Let  $S = \text{span}\{\mathbf{x}, \mathbf{y}\}$ . Now  $\mathbf{z} \in S^\perp$  means that  $\mathbf{x}^T \mathbf{z} = \mathbf{y}^T \mathbf{z} = 0$ . Put it in matrix form

$$\begin{bmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix},$$

i.e.,  $\mathbf{z} \in N(A)$  where  $A = \begin{bmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{bmatrix}$ .

(b) Solving

$$\left[ \begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 1 & -1 & 2 & 0 \end{array} \right] R_2 - R_1 \left[ \begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & -3 & 1 & 0 \end{array} \right]$$

So  $z_3 = t$ ,  $z_2 = \frac{1}{3}t$  and  $z_1 = -2z_2 - z_3 = -\frac{5}{3}t$ , i.e.,  $\mathbf{z} = \frac{t}{3}(-5, 1, 3)^T$ . So  $\{(-5, 1, 3)^T\}$  is a basis of  $S^\perp$ .

4 Similar to Exercise 3, solving

$$\left[ \begin{array}{cccc|c} 1 & 0 & -2 & 1 & 0 \\ 0 & 1 & 3 & -2 & 0 \end{array} \right]$$

So  $x_4 = t$ ,  $z_3 = s$ ,  $z_2 = -3s + 2t$  and  $z_1 = 2s - t$ , i.e.,  $\mathbf{z} = (2s - t, -3s + 2t, s, t)^T = s(2, -3, 1, 0)^T + t(-1, 2, 0, 1)^T$ . So  $\{(2, -3, 1, 0)^T, (-1, 2, 0, 1)^T\}$  is a basis of  $S^\perp$ .